

Fidelity Metrics for Virtual Environment Simulations based on Spatial Memory Awareness States

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Abstract

This paper describes a methodology based on human judgments of memory awareness states for assessing the simulation fidelity of a Virtual Environment (VE) in relation to its real scene counterpart. In order to demonstrate the distinction between task performance based approaches and additional human evaluation of cognitive awareness states, a photorealistic VE was created. Resulting scenes displayed on a Head Mounted Display (HMD) with or without head tracking and desktop monitor were then compared to the real world task situation they represented investigating spatial memory after exposure. Participants described how they completed their spatial recollections by selecting one of four choices of awareness states after retrieval in an initial test and a retention test a week after exposure to the environment. These reflected the level of visual mental imagery involved during retrieval, the familiarity of the recollection and also included guesses, even if informed. Experimental results revealed variations in the distribution of participants' awareness states across conditions while, in certain cases, task performance failed to reveal any. Experimental conditions which incorporated head tracking were not associated with strong visually-induced recollections. Generally, simulation of task performance does not necessarily lead to simulation of the awareness states involved when completing a memory task. The general premise of this research focuses on *'how'* tasks are achieved, rather than only on *'what'* is achieved. The extent to which judgements of human memory recall, memory awareness states and presence in the physical and VE are similar provides a fidelity metric of the simulation in question.

1. Introduction

The mapping from the real world environment to the computer graphics environment is mediated by *environmental* or *visual* fidelity (Waller, Hunt & Knapp, 1998). The term *visual fidelity* refers to the degree to which visual features in the Virtual Environment (VE) conform to visual features in the real environment. *Interface or interaction fidelity* refers to the degree to which the simulator technology (visual and motor) is perceived by a trainee to duplicate the operational equipment and the actual task situation. It is argued that training, for instance, in a VE with maximum fidelity would result in transfer equivalent to real-world training since the two environments would be indistinguishable (Waller, Hunt & Knapp, 1998). Robust metrics are essential in order to assess the fidelity of VE implementations comprising of computer graphics imagery, display technologies and 3D interaction metaphors across a range of application fields. Apart from optimisation of technological characteristics such as resolution, Field-of-View (FoV), latency, etc., one common belief is that efficient task performance measures should serve as fidelity metrics for any application that mainly targets transfer of training in the real world (Bailey & Witmer, 1994, Waller, Hunt & Knapp, 1998, Lathrop & Kaiser, 2002). A commonly employed strategy, therefore, for assessing the simulation fidelity of a VE is to compare task performance in a VE to task performance in the real world scene represented in the VE. Another common approach is to employ a cross-application construct, such as the sense of ‘presence’ to assess the effectiveness of a VE or aspects of a VE according to its success in enhancing presence. There is a widespread belief that presence should somehow improve task performance, although this has yet to be verified or indeed reasons offered as to why this should be the case (Stanney et al., 1998).

This paper argues that because of the wide-range of VE applications and differences in participants across their background, ability and method of processing information, an understanding of *how* tasks are undertaken within a VE complementing *what* is achieved, is significant. This rationale is applied here to spatial memory recall. The utility of VEs, regardless of the applications they are proposed for is predicated upon the accuracy of the spatial representation formed in the VE. The framework to be presented has been drawn from traditional memory research adjusted to form an experimental procedure in order to compare real scenes and their computer graphics simulated counterparts. Here, participants could describe how they achieved their spatial recollections after exposure to an environment by selecting one of four awareness states (‘remember’, ‘know’, ‘familiar’ or ‘guess’) (Tulving, 1985, 1993, Conway, Gardiner, Perfect & Anderson, 1997, Gardiner, 2000). These judgments reflect the level of visual mental imagery involved at retrieval and the familiarity of the recollection including guesses, even if informed. In order to demonstrate the varied

distribution of cognitive activity even when task performance remains the same, a photorealistic VE was created displayed on a Head Mounted Display (HMD) - incorporating either mono or stereo rendering with or without head tracking - and desktop display. Resulting scenes were then compared to the real-world task situation they represented employing memory recall of elements of the space as well as report of awareness states on an initial test and a retention test a week after the initial exposure. Central to this work is identifying whether experimental conditions such as the real-world one and those incorporating head tracking (thus including proprioceptive information) are associated with stronger visually-induced recollections ('remember' awareness state) compared to conditions associated with a typical mouse interaction interface. This work also aims to explore whether a cognitive shift between initial test and retest is going to signify a performance shift. This study extends a preliminary study by Mania & Chalmers, 2001.

2. Background

2.1 Spatial Training in Synthetic Worlds

The first effort to compare real and simulated computer graphics *static* scenes side by side was attempted by Meyer, Rushmeier, Cohen & Greenberg, 1986. Radiometric values predicted using a radiosity rendering of a basic scene were compared to physical measurements of radiant flux densities in the real scene both of which were viewed through the back of a view camera. In a more recent approach, McNamara, Chalmers, Troscianko & Gilchrist, 2000 described a method for measuring the perceptual equivalence between a real scene and static computer simulations of the same scene based on human judgements of lightness. Results showed that rendering solutions such as tone-mapping were of the same perceptual quality as a photograph of the real scene.

For *real-time* VE applications, a central research issue for training could be how participants mentally represent an interactive computer graphics world and how their recognition and memory of such worlds correspond to actual conditions. Waller Hunt & Knapp 1998, Bailey & Witmer, 1994 and Bliss, Tidwell & Guest, 1997 examined the variables that communicate transfer of spatial knowledge and discuss the form and development of spatial representation in VE training in relation to either real-world training or training with maps, photographs and blueprints. The suitability of VE systems as effective training mediums is examined and concluded to be as effective as map or blueprint training (Waller Hunt & Knapp 1998, Bliss et al., 1997) with configurational knowledge acquisition similar to training with photographs and real world training (Bailey & Witmer, 1994). Dinh, Waler & Hodges, 1999 investigated

the effects of tactile, olfactory, audio and visual sensory cues on participants' memory recall of a building. Two levels of visual detail were investigated by reducing texture resolution with or without ambient auditory stimulation, olfactory stimulation and tactile stimulation. No significant main effect was revealed on spatial layout recall. Accurate recall of objects' locations was significantly higher when tactile cues and olfactory cues were incorporated in their environment. Arthur, Hancock & Chrysler, 1997 examined participants' ability to reproduce a complex spatial layout of objects having experienced them previously under different viewing conditions (a free binocular virtual condition, a free binocular real-world condition and in a single viewpoint monocular view of the real world). Mapping results showed a significant effect of viewing condition where, interestingly, the static monocular condition was superior to both the active virtual and real binocular conditions.

Experimental post exposure methodologies for spatial recall investigation range from questionnaires (Dinh, Waler & Hodges, 1999) to drawing sketches of a space after exposure (Billingshurst & Weghorst, 1993) or applying the spatial knowledge acquired so as to navigate effectively the real world space represented (Waller Hunt & Knapp 1998, Bailey & Witmer, 1994, Bliss, Tidwell & Guest 1997). Performance accuracy is the dominant means of assessing a VE simulation. In this paper, performance accuracy is complemented by self-report of the cognitive activity (awareness states) during retrieval, utilising a memory task and a retention memory test a week after exposure across real-world and photorealistic VE viewing conditions.

2.2 Memory Awareness States Methodology

Memory, in the sense of 'information' for subsequent analysis, plays an important role in perceptual systems such as the visual, auditory, haptic and kinesthetic. Memory is not a unitary system (Baddeley, 1997). In the process of acquiring a new knowledge domain, visual or non-visual, information retained is open to a number of different states. Some elements of a learning experience or of a visual space may be 'remembered' linked to a specific recollection event and mental image or could just pop-out, thus, could be just 'known'. According to Tulving, 1985 recollective experiences are the hallmark of the episodic memory system. Knowing refers to those in which there is no awareness of re-living any particular events or experiences, a mental thesaurus (semantic memory). Tulving, 1985 introduced a distinction between '*remember*' and '*know*' responses and provided the first demonstration that these responses can be made in a memory test, item by item out of a set of memory recall questions, to report awareness states as well. He reported illustrative experiments in which participants were instructed to report their states of awareness at the time they recalled or recognised words they had previously encountered in a study list. If they remembered what they

experienced at the time they encountered the word, they made a 'remember' response. If they were aware they had encountered the word in the study list but did not remember anything they experienced at that time, they expressed a 'know' response. The results indicated that participants could quite easily distinguish between experiences of remembering and knowing.

There is some preliminary evidence that the distinction between 'remembering' and 'knowing' reflects a difference in brain activity at the time of encoding (Smith, 1992). It is assumed that recognition memory can be based largely on knowing, with little or no remembering. All that is necessary for encoding into the semantic system is some initial awareness of events. In contrast, encoding into episodic memory must depend on greater conscious elaboration of the events. Greg & Gardiner, 1994 showed that estimates of the strength of the memory trace are greater when derived from remember plus know responses than when derived from only remember responses. Knowing, thus, reflects an additional source of memory, not merely a difference in response criteria. Although, 'remember' and 'know' awareness states have been controversially linked to episodic and semantic memory types with 'know' responses more theoretically problematic, recent research emphasised that 'they can be used without commitment to any theory, but simply to provide information on how various phenomena, including memory disorders, are characterised experientially' (Gardiner, 2000). In a relevant study, overall recognition performance in two groups of participants was very similar, however, the reported states of awareness differed markedly. One cannot make assumptions on what participants experience mentally from only their performance, therefore, there is no alternative to the use of subjective reports. Thus, additional information of awareness states provides an invaluable input into 'how' participants complete recollections. Subsequent research to Tulving, 1985, summarised in Gardiner, 2000 demonstrated that some variables affect one or the other of the two states of awareness, that some variables have opposing effects on them and that some variables have parallel effects on them. This finding indicates that the two states of awareness are functionally independent.

Conway, Gardiner, Perfect, Anderson & Cohen, 1997 argued that 'familiarity' can be defined as the feeling that something has been encountered or experienced recently, although nothing about this recent occurrence can be remembered. 'Know' responses, on the other hand, represent highly familiar memory items that may come to mind without recollecting any particular encounter or any feeling of a recent encounter and cannot be placed. Conway, Gardiner, Perfect & Anderson, 1997 showed that these finer grained judgements could be

dissociated from each other, just as different source memory judgements can. ‘Remember’ and ‘Know’ awareness states would get assigned to more confident recollections (but communicating different awareness states) and ‘familiar’ and ‘guess’ respectively to less confident recollections. A confidence scale cannot communicate awareness states. It is also suggested that when a new knowledge domain is to be acquired, memory is represented initially in an episodic way. As time goes by, the underlying representations may change such that they do not represent recollective experiences and are simply ‘known’ leading to a semantic representation and schematised conceptual knowledge. There is little evidence that feelings of familiarity reflect the semantic memory system that supports highly familiar long-term knowledge. Gardiner, 2000, concludes: ‘... psychology of memory should take on board subjective reports of conscious states and not just rely on more conventional measures of performance. This evidence has established that the essential subjectivity of remembering and knowing does not make reports of these states of awareness intractable to science’.

3. Experimental Methodology

3.1 Experimental design

Five groups of 21 participants were recruited to participate in this study, from the University of Bristol, UK undergraduate and M.Sc. student population and they received course credits for their participation. 80% of the participants from each group were male. All used computers a great deal in their daily activities. A between-subject design was utilised balancing groups for age and gender. Participants in all conditions were informed that they could withdraw from participation at any time during the experiments and they were naive as to the purpose of the experiment. Participants had either normal or corrected-to-normal vision (self-report). According to the group they were assigned to, participants completed the same memory task in one of the following conditions:

- 1) In reality, wearing custom made goggles to restrict their FoV, allowing for monocular vision; referred to as the **real-world condition**.
- 2) Using a photorealistic computer graphics simulation on a monocular head-tracked HMD; referred to as the **HMD mono head tracked condition**.
- 3) Using the same application on a stereo head-tracked HMD; referred to as the **HMD stereo head tracked condition**.
- 4) Using the same application on a monocular HMD with a mouse interface; referred to as the **HMD mono mouse condition**.

- 5) Using the same application displayed on a typical desktop monitor with a mouse interface, wearing the same restrictive goggles as in the real-world condition; referred to as the **desktop condition**.

A week after their experience, all participants were retested on the same memory task.

3.1.1 The Real Environment

The real environment consisted of a four by four meters room (Figure 1). Each wall of this room had a different landmark; one wall consisted of a door and shelves, one wall of a door and a greenboard, the third wall of a whiteboard and the fourth of smaller shelves on both its ends. The existing window in the room was firmly covered with black lining to keep natural light out. The light fixtures in the room were replaced with a standard incandescent bulb (assumed diffuse, light emission in all directions). Several tables were placed close to the walls and 21 primitive objects of approximately the same size (seven boxes, seven spheres and seven pyramids) were scattered around the room, on the tables and shelves. All the objects were painted one shade of blue using the same diffuse paint. A swivel chair was placed in the middle of the room.

3.1.2 The Computer Graphics Simulation

There was tight control over the visual appearance of the experimental space across real-world and simulated conditions. The geometry in the real room was measured using a regular tape measure with accuracy of the order of one centimetre. A photometry instrument (Minolta Spot Chroma meter CS-100) was employed to measure the chromaticity CIE(x,y) and luminance (Y) values of the light and materials in the real room. The Minolta chroma meter is a compact, tristimulus colorimeter for non-contact measurements of light sources or reflective surfaces. Luminance relates to the quality of a colour that most resembles the human's notion of brightness. Bright colours are generally of a high luminance and dark colours are generally of a low luminance. The illuminant (light source) was measured by placing a white sheet of paper in a specific position. Most of the materials (walls, objects, shelves, floor, plugframes) were measured at the same position. To ensure accuracy, five measurements were recorded for each material, the highest and lowest luminance magnitudes were discarded and an average was calculated of the remaining three triplets. However, as this is a room in daily use some variations exist in all of the surfaces due to texture, ageing and dirt.

The CIE (1931) colour space is based on colour matching functions derived by human experimentation and it incorporates the trichromacy of the HVS. The usefulness of the

CIE(x,y) representation is that it allows colour specification in one language, however, equal geometric steps of CIE(x,y) space do not correspond to equal perceptual steps. Before specifying display colours, it is necessary to compute the tristimulus matrix of the display in question. In order to compute the RGB tristimulus matrix, the chromaticity co-ordinates of the three display phosphors in CIE(x,y) space are required. In addition, the chromaticity co-ordinates of the white that the three phosphors of the display produce when turned on at their maximum are also required (Travis, 1991). Generally, the RGB system is a means for describing colours on a display monitor. It does not take into account the energy that is produced in the physical world in terms of the distribution over wavelength and also how the Human Visual System (HVS) responds to this distribution.

For the final measurements, the illuminant had to be taken into account. Measuring a diffuse surface under a given light source results in Y_{xy} values which include the contribution of the light source itself. Incandescent bulbs are quite orange and fluorescent light is quite green, however, the HVS perceives light in relative values and not as absolute measurements such as the ones out of the chromameter. For example, if 1000 is the luminance in the real world, 100 the luminance of a real-world material but 100 the luminance in the computer graphics simulation, then the luminance for the *simulated* material needs to be 10 for the same *ratio* to be preserved. The colour constancy attribute of the HVS, generally, is responsible for humans perceiving a white sheet of paper as white under a wide range of illumination. If a participant is *immersed* into a synthetic space on a display, theoretically, this should be true as well, however, the small size of the displays prevents colour constancy from occurring. In relevant calculations for simulating real-world illumination in a synthetic world, therefore, colour constancy needs to be enforced in the rendering process since the HVS does not function as in the real world due to the nature of the displays. The colour of the illuminant in RGB values was set as (1,1,1) for the radiosity rendering, e.g. white.

In order to render the scene, the materials' diffuse colour needs to be specified not the colour observed under a particular light source. The final colour for each measured material in the scene is estimated by dividing its RGB value by the RGB value of the observed white in the scene, which is the colour of the light source in the scene. Using the relevant geometry and surfaces and illuminant measurements converted to RGB triplets as input, the rendered model was created using a radiosity rendering system (Figure 2). The final radiosity solution consisted of a finely meshed model which could be interactively manipulated. This was the basis for the application displayed on the desktop monitor and on the HMD. The desktop monitor and the HMD were gamma corrected using the Minolta Spot Chromameter CS-100 in

order to acquire relevant luminance readings. When accurate colour specification is required as is often the case in scientific applications, the non-linear relationship between display luminance and voltage is a significant source of error and needs to be corrected to linearity.

3.2 Materials

The five groups of participants were asked to fill in the same set of questionnaires. This set included the SSQ questionnaire (Kennedy, Lane, Berbaum & Lilienthal, 1993) before and after the task, the memory task and memory awareness states questionnaire and the presence questionnaire (Slater, Steed, McCarthy & Maringelli, 1998). All participants across the five conditions completed the same memory task a week after the initial experiment reporting on memory recall, confidence and awareness states.

3.2.1 Memory recall task

The memory recall questionnaire was designed to test the participants' memory recall of the positions and geometric shape of the 21 objects in the room. A diagram for each wall in the room included numbered positions of objects in various locations. The diagrams were administered together with the task questionnaire which consisted of 21 multiple-choice questions representing the 21 objects in the scene (Figure 3). Every question included three possible answers (box, sphere or pyramid) and a confidence scale with five possible states: No confidence, Low confidence, Moderate confidence, Confident, Certain. Every question also included an awareness states report for every recollection, based on the memory awareness methodology offering four choices: Remember, Know, Familiar or Guess. The participants were required to report on the shape of the object in each numbered position on the diagram, starting with the positions they were more confident they remembered. The design, thus, of the task questionnaire did not force participants to start from a specified position in the room offering the capability to report, initially, their most confident recollections. A pilot study was conducted in order to determine the number of objects and, therefore, the number of questions of recall in relation to the exposure time so as to avoid possible floor or ceiling effects (the task being too easy or too hard). Prior to filling out the core of the task questionnaire, participants were given instructions designed to explain what the memory awareness states depicted as follows:

- REMEMBER means that you can visualise clearly the object in the room in your head, in that particular location. You virtually 'see' again elements of the room in your mind.

- KNOW means that you just ‘know’ the correct answer and the alternative you have selected just ‘stood out’ from the choices available. In this case you can’t visualise the specific image or information in your mind.
- FAMILIAR means that you did not remember a specific instance, nor do you know the answer. It may seem or feel more familiar than any of the other alternatives.
- GUESS means that you may not have remembered, known, or felt that the choice you selected have been familiar. You may have made a guess, possibly an informed guess, e.g. you have selected the one that looks least unlikely.

3.2.2 Other measures

The presence questionnaire developed by Steed, McCarthy & Maringelli, 1998 was designed to measure the level of presence on a Likert 7-point scale and was administered after the initial memory recall task across conditions. The widely used Simulator Sickness questionnaire (SSQ) was administered before and following participants’ exposure across conditions (Kennedy, Lane, Berbaum & Lilienthal, 1993).

3.3 Procedures

3.3.1 The real-world condition

The SSQ questionnaire was administered before exposure. Following this procedure participants were asked to wear any glasses or contact lenses they normally use when they have to focus at 2 meters distance (self-report). Subsequently, their dominant eye was identified by a widely used ‘sighting’ test. A pre-determined viewing position was set by manipulating the height of the swivel chair according to the individual. Appropriate goggles were worn which restricted participants’ FoV to 30 degrees to match the desktop and HMD’s FoV allowing for monocular vision through the dominant eye only (Figure 4). The FoV was restricted in the real-world condition to match the FoV of the displays. Although this action resulted in a ‘window’ to the real world through the goggles, it was considered necessary in order to keep the FoV constant across conditions. Participants were instructed that they would be guided to a room where they would spend three minutes observing by rotating the swivel chair they would sit on placed in the middle of the room, however, they were not aware of the post-exposure task. Navigational patterns and idle time were monitored and recorded during exposure through a digital compass attached on the swivel chair (Mania & Randell, 2002). After the set exposure time of three minutes, participants were guided to the test room where the questionnaire pack was administered together with the appropriate instructions.

3.3.2 The display conditions

The computer graphics application was displayed on a Kaiser Pro-View 30, gamma corrected HMD (Figure 4). The viewpoint was set in the middle of the room and navigation was restricted to a 360 degrees circle around that viewpoint and 180 degrees vertically in order to simulate participants' movement on the swivel chair in the real room (3 degrees of freedom). The geometric FoV was calculated to be the same as the visual angle, through the goggles, in the real room. For the HMD monocular conditions (head-tracked and non-head-tracked) the dominant eye was identified and the appropriate screen of the HMD was covered allowing for vision only through the dominant eye. For the HMD stereo head tracked condition each participant's interpupillary distance (IPD) was measured and the stereo application's parallax was set accordingly for the individual. For the desktop condition utilizing a gamma corrected typical 21-inch desktop monitor, each participant's dominant eye was identified and the appropriate goggles were subsequently worn as in the real-world condition. The frame of the monitor was covered with black cardboard to achieve a foreground occlusion effect resulting in a stronger sense of depth. Horizontal rotation was monitored across all conditions (Mania & Randell, 2002). There was no other source of light besides the HMD or desktop display during exposure. The frame rate was retained at 14 frames per second across all conditions. Although this is not a particularly high frame rate, it was considered adequate. The display resolution was 640*480 (HMD maximum resolution) across technological conditions and the FoV was constant (30 degrees) across all conditions including the real-world condition with restrictive goggles fitted. The computer graphics rendering was computed taking into account real world photometric measurements resulting in a photorealistic rendering as described in the previous section. Texture mapping was applied only on the doors and tables in the room.

4. Results and Discussion

4.1 Memory Awareness States' Statistical Analysis

Awareness state data were represented as *prior* and *posterior* probabilities. Koriat & Goldsmith, 1994 have drawn an important distinction between the amount or quantity remembered compared to the accuracy or quality of what is remembered. In the quantity analysis memory awareness states data are represented as *a priori* or *prior probabilities*. Although this notation does not follow the Bayesian probability theory principles for 'prior' probabilities, it is going to be adopted as such in this paper following the characterisations of Koriat & Goldsmith, 1994 as well as Conway, Gardiner, Perfect, Anderson & Cohen, 1997. Prior probabilities are obtained by calculating the proportions of correct answers falling in

each of the four memory awareness categories for each participant. In the accuracy analysis, correct recall scores are represented as *posteriori* or *posterior probabilities*. In order to calculate posterior probabilities, the proportion of correct answers from the total of answers given in each memory awareness category is computed for each participant.

For participant n ,

x_{in} is the number of correct answers for the i awareness state,

x'_{in} is the number of incorrect answers for the i awareness state,

$i = \{\text{remember, know, familiar, guess}\} = \{1,2,3,4\}$

then,

P_{in} is the prior probability for awareness state i related to participant n (Equation 3.1),

$$P_{in} = \frac{x_{in}}{\sum_{i=1}^4 x_{in}}$$

P'_{in} is the posterior probability for awareness state i related to participant n (Equation 3.2),

$$P'_{in} = \frac{x_{in}}{x_{in} + x'_{in}}$$

Generally, prior probabilities reflect the following: Given that the response of a participant is correct, what is the probability that the participant has chosen a particular state on that question? Posterior probabilities, on the other hand, pose the following question: Given that a response of a participant was assigned to one of the four memory awareness response categories, what is the probability that the response is correct? For the purpose of this study each memory recall question included a 5-scale confidence scale and a choice between ‘remember’, ‘know’, ‘familiar’ as well as ‘guess’ awareness states. The goal of this strategy was to identify the distributions of awareness states responses across conditions focusing on visually induced recollections. This could reveal variations that wouldn’t be possible by just counting right and wrong answers.

4.2 Spatial Memory Recall and Memory Awareness States Results

The participants completed the memory task including confidence and awareness responses across the five conditions. The memory recall scores for the initial task and retest, the confidence scores as well as the prior and posterior probabilities derived from the memory awareness states dataset were analysed using ANalysis of VAriance (ANOVA). ANOVA is a powerful set of procedures used for testing significance where two or more conditions are used. Significance decisions involve rejecting or retaining the null hypothesis (which claims that groups are identical). The null hypothesis is rejected when the probability that a result occurring under it is less than .05 (Coolican, H., 1999).

The total number of objects that were correctly located and indentified was counted for each participant after completing the initial test as well as the retention test a week after. The memory performance measures were subjected to a 5 (viewing condition) x 2 (testing session) mixed ANOVA with viewing condition as a between-subjects factor and testing session as a within-subjects factor, with number of correct responses as the dependent variable. Table 1 shows the mean accurate recall scores and standard deviations (in parenthesis) as a function of viewing condition and test/retest session. All effects were evaluated at a p-level of 0.05 to determine statistical significance. There was a significant main effect for testing session ($F(1,100)=36.51$, $p<0.01$) but not for viewing condition ($F(4,100)=1.47$, $p>0.05$). The interaction between testing session and viewing condition was not significant ($F(4,100)=0.59$, $p>0.05$). These results show that participants had retained significantly less spatial information over time, however, the viewing condition had no effect on the decrease of recall performance.

A confidence measure was included for each recollection. The confidence scores were subjected to a 5 (viewing condition) x 2 (testing session) mixed ANOVA with viewing condition as a between-subjects factor and testing session as a within-subjects factor, with the confidence selection (No confidence=1, Low confidence=2, Moderate confidence=3, Confident=4, Certain=5) as the dependent variable. Table 1 shows the mean confidence scores and standard deviations (in parenthesis) as a function of viewing condition and test/retest session. There was a significant main effect for testing session ($F(1,100)=183.59$, $p<0.01$) but not for viewing condition ($F(4,100)=1.84$, $p>0.05$). Also, the interaction between testing session and viewing condition was not significant ($F(4,100)=0.53$, $p>0.05$). These results show that participants had significantly less confidence over time while completing the memory task, however, the viewing condition had no effect on the decrease of confidence.

Table 2 shows the mean prior probabilities and standard deviations (in parenthesis) as a function of viewing condition and test/retest session. Prior probabilities indicate the proportion of correct answers under each memory awareness state. The prior probabilities were subjected to a 5 (viewing condition) x 4 (awareness state) x 2 (testing session) mixed ANOVA with viewing condition as a between-subjects factor and both awareness session and testing session as within-subjects factors. There was a significant main effect for awareness state ($F(3,300)=11.17$, $p<0.05$) but not for viewing condition. The interaction between awareness state and viewing condition was significant ($F(12,300)=1.8$, $p<0.05$). The interaction between awareness state and testing session was also significant ($F(3,300)=42.4$, $p<0.05$). One-way ANOVA and Tukey's Post-Hoc tests were applied following the significant interaction between awareness state and viewing condition separately for the initial task and retest. There was a significant main effect of condition upon the 'remember' awareness state, $F(4,104)=3.016$, $p<0.05$, and a tendency of significance for the 'know' awareness state, $F(4,104)=1.913$, $p<0.1$. In particular, the probability that correct responses would be linked with the 'remember' awareness state was significantly higher for the HMD mono mouse condition compared to the HMD mono head tracked and HMD stereo head tracked conditions ($p<0.05$). No significant effects were revealed for the retest. The three-way interaction between viewing condition, awareness state and testing session was not significant. A thorough inspection of the prior probabilities means reveals that correct 'remember' responses dramatically declined over time and correct 'guess' responses substantially increased over time. A possible interpretation could be that correct 'remember' responses were converted to correct 'guess' responses at the retest, with correct 'know' and 'familiar' responses comparatively slightly changed.

Table 3 shows the mean posterior probabilities and standard deviations as a function of viewing condition and test/retest session. Posterior probabilities represent the probability that a memory recall response assigned to each of the memory awareness states is accurate. Posterior probabilities related to the 'familiar' and 'guess' awareness states were calculated for the retest. A small number of participants selected the 'remember' and 'know' awareness states resulting in posterior probabilities not being calculated reliably. The posterior probabilities were subjected to a 5 (viewing condition) x 4 (awareness state) mixed ANOVA with viewing condition as a between-subjects factor and awareness session as a within-subjects factor, separately for test and retest. For the initial task, there was a significant main effect for awareness state ($F(3,150)=19.70$, $p<0.05$) but not for viewing condition ($F(4,50)=1.20$, $p>0.05$). The interaction between viewing condition and awareness state was

not significant ($F(12,150)=0.98, p>0.05$). For the retest, there was a significant main effect for awareness state ($F(1,89)=9.47, p<0.05$) and for viewing condition ($F(4,89)=2.62, p<0.05$). The interaction between viewing condition and awareness state was not significant ($F(4,89)=1.29, p>0.05$). A subset of participants was included in this analysis due to the issues mentioned above.

Generally, incorporating awareness states in a memory test connects memory recall with cognitive activity and forms a framework which investigates 'how' humans mentally represent a space from a cognitive point of view rather than a task performance point of view. Such metrics could form an integral part of the significant performance efficiency measures.

4.3 Presence and Simulator Sickness Results

The presence questionnaire was administered after the initial task was completed. A binomial regression analysis was employed based on the count of high scores out of six presence questions and following the analysis discussed in the Slater, Steed, McCarthy & Maringelli 1998 study. 0 was assigned if the count of high scores was 0-2 and 1 if the count of high scores was 3-6. Binomial regression, generally, shows the probability of falling under one of the 0 or 1 binomial distributions. An overall effect of condition was not revealed. Similar effects of condition on presence were revealed in studies where the validity of the questionnaire is examined (Usoh, Catena, Arman & Slater, 2000). The questionnaire may have failed to pick up the difference across conditions or there was not any due, for instance, to the high quality of the rendering. A concrete understanding of presence, in a way that will allow formal assessments of its perceived level in experimental studies such as this one (if this is ever possible or desirable) will aid towards forming relevant conclusions. The Simulator Sickness Questionnaire (SSQ) scores (Kennedy, Lane, Berbaum & Lilienthal, 1993) were low due to the short exposure time.

5. Discussion

This investigation focuses on the effect of different viewing conditions (direct perception of objects in a real-world setting versus perception of the computer graphics representation of this setting) on observers' attributions regarding object-location memory. Accuracy of performance per se is an imperfect reflection of the cognitive activity that underlies performance in memory tasks. Accurate memory can be supported by either a recollection of prior specific experience (remembering) or reliance on a general sense of knowing with little or no recollection of the source of this sense (knowing) including familiarity and guesses even if informed. Training in a VE system capable of perfectly simulating the real world should

result in the same training effect as that in the real world. The participants who mentally visualised the room and the objects in the room during retrieval had a higher proportion of correct responses under the 'remember' awareness state. The participants that employed mnemonics' strategies based on words instead of visually retaining elements of the space reported the 'know' awareness state which resulted in a proportion of correct responses linked with the 'know' awareness state. If a weaker trend of non-visually induced recollections is employed by participants towards stronger visually induced recollections linked to the 'remember' awareness state, it could be assumed that their mental representation of a space involved more 'vivid' recollections.

There was a significant main effect of condition upon the 'remember' awareness state. It was anticipated that the amount of correct 'remember' responses would be higher in conditions incorporating more 'naturalistic' interfaces such as head tracking. However, results revealed that the proportion of correct responses linked with the 'remember' awareness state was significantly higher for the HMD mono mouse condition compared to the HMD mono head tracked and HMD stereo head tracked conditions (initial task). Therefore, an interface of high simulation fidelity such as head tracking does not always correspond to visually induced memory awareness states. A similar result was revealed in a preliminary study by Mania & Chalmers, 2001. If specific applications require a high amount of recollections based on visual mental imagery, a 'natural' interface such as head tracking may not be appropriate. Therefore, desirable variations of awareness states for specific application purposes could be identified. It could be true, for instance, that for flight simulation applications it is crucial for trainees to achieve a high level of visually induced recollections related to instruments as opposed to feelings of familiarity of even confident recollections which are not accompanied by visual imagery. If 'reality' is associated to the degree of similarity to the real world task situation then, in this case, the HMD mono mouse condition is not very 'real'. The awareness states distribution is affected by the degree of 'realism' of the motor response. Word based mnemonics and, generally, recollections that were not linked to visually induced recollections were identifiable by the high proportion of correct 'know' responses. The utilisation of a viewing method such as the HMD together with an 'unreal' motor response such as the mouse, appeared to have prevented participants employing non-visually induced recollections and resulted in a larger distribution of correct responses assigned to the 'remember' awareness state. By decreasing the degree of 'reality' of the motor response, participants - paradoxically- adopted visually induced recollections. Achieving high fidelity could incorporate the need for similar awareness states between a real-world task situation and its computer graphics simulation. Here, something less 'real', therefore, less computationally

expensive but more demanding because of its novelty may restore a more 'naturalistic' or desirable awareness state. Research could identify such issues by using methodologies that allow investigations based on the cognitive activity expressed by awareness states responses. Additionally, a significant shift of correct 'remember' responses in the initial task to correct 'guess' responses in the retest was observed. This shift was observed across all conditions and it did signify a lower amount of correct recollections between initial test and retest.

The task employed in this study did not allow for free navigation around the experimental space. The FoV was restricted in the real-world setting to match the FoV of the displays for methodological reasons. Future work could include a task which would allow freedom of navigation and also a testing strategy which would incorporate transfer of training in the real-world. Matching participants' performance in simulations to performance in a real-world situation does not guarantee that the cognitive activity linked with performance will be similar across the simulated conditions. Task performance scores could, therefore, be taken into account according to specific awareness states. By employing methodologies, such as the memory awareness states methodology, computer graphics and VE technology research could exploit human perceptual mechanisms towards successful applications.

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Figure 1: The real world room (real-world condition).



Figure 2: The radiosity rendering.

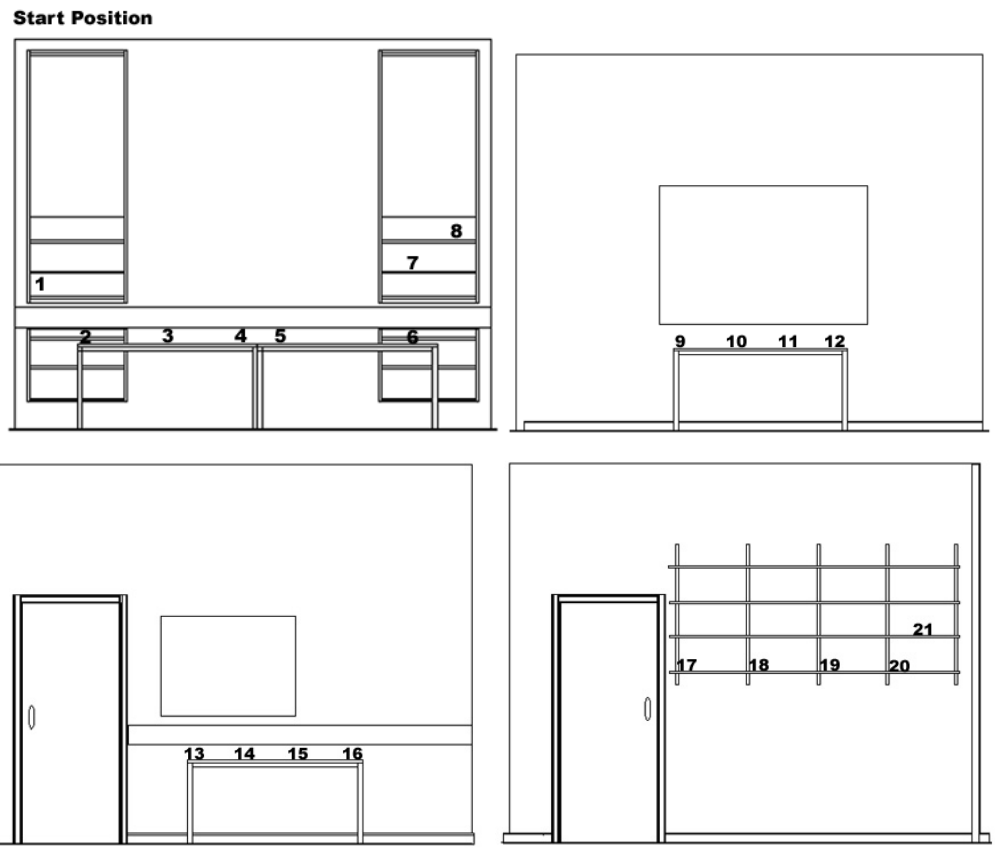


Figure 3: Diagrams utilised for memory recall testing, for each wall of the room.



Figure 4: The real-world and HMD mono/stereo condition (head-tracked).

| Viewing Condition N=105 | Recall | Recall | Confidence | Confidence |
|----------------------------|--------------|--------------|--------------|-------------|
| | performance | performance | | |
| | Initial test | Retest | Initial test | Retest |
| Real world | 12.42 (4.29) | 10.14 (4.60) | 3.22 (0.78) | 2.50 (0.77) |
| HMD mono head tracked | 12.25 (5.05) | 10.75 (4.41) | 2.93 (0.85) | 2.05 (0.86) |
| HMD stereo head tracked | 10.89 (3.63) | 9.42 (3.80) | 2.66 (0.63) | 1.94 (0.83) |
| Desktop | 10.90 (3.94) | 8.00 (3.53) | 2.94 (0.55) | 2.27 (0.64) |
| HMD mono mouse | 10.56 (3.21) | 8.34 (3.21) | 2.99 (0.60) | 2.15 (0.73) |

Table 1: Means and Standard deviations for accurate memory recall performance and confidence scores as a function of viewing condition (N total number of participants).

| Viewing Condition | Remember Test | Remember Retest | Know Test | Know Retest | Familiar Test | Familiar Retest | Guess Test | Guess Retest |
|-------------------------|---------------|-----------------|-------------|-------------|---------------|-----------------|-------------|--------------|
| N=105 | | | | | | | | |
| Real world | 0.33 (0.25) | 0.16 (0.25) | 0.26 (0.25) | 0.15 (0.24) | 0.27 (0.24) | 0.33 (0.28) | 0.12 (0.16) | 0.34 (0.29) |
| HMD mono head tracked | 0.27 (0.30) | 0.04 (0.09) | 0.25 (0.29) | 0.13 (0.24) | 0.24 (0.21) | 0.29 (0.20) | 0.22 (0.20) | 0.53 (0.29) |
| HMD stereo head tracked | 0.24 (0.23) | 0.10 (0.19) | 0.16 (0.19) | 0.07 (0.16) | 0.39 (0.3) | 0.37 (0.26) | 0.18 (0.18) | 0.44 (0.29) |
| Desktop | 0.29 (0.24) | 0.04 (0.09) | 0.20 (0.18) | 0.13 (0.24) | 0.28 (0.2) | 0.29 (0.2) | 0.2 (0.18) | 0.53 (0.29) |
| HMD mono mouse | 0.49 (0.22) | 0.09 (0.15) | 0.10 (0.14) | 0.20 (0.27) | 0.22 (0.18) | 0.27 (0.22) | 0.17 (0.17) | 0.41 (0.34) |

Table 2: Prior probabilities and standard deviations as a function of viewing condition and test/retest session (N total number of participants).

| Viewing Condition | Remember Test, N=55 | Remember Retest | Know Test, N=55 | Know Retest | Familiar Test, N=55 | Familiar Retest, N=94 | Guess Test, N=55 | Guess Retest, N=94 |
|-------------------------|---------------------|-----------------|-----------------|-------------|---------------------|-----------------------|------------------|--------------------|
| Real world | 0.90 (0.31) | - | 0.62 (0.37) | - | 0.47 (0.30) | 0.44 (0.30) | 0.60 (0.33) | 0.41 (0.23) |
| HMD mono head tracked | 0.85 (0.25) | - | 0.73 (0.33) | - | 0.49 (0.34) | 0.49 (0.27) | 0.46 (0.26) | 0.47 (0.10) |
| HMD stereo head tracked | 0.77 (0.31) | - | 0.49 (0.35) | - | 0.49 (0.33) | 0.55 (0.19) | 0.27 (0.31) | 0.33 (0.21) |
| Desktop | 0.65 (0.43) | - | 0.68 (0.33) | - | 0.43 (0.31) | 0.46 (0.26) | 0.43 (0.32) | 0.32 (0.22) |
| HMD mono mouse | 0.88 (0.19) | - | 0.53 (0.37) | - | 0.38 (0.32) | 0.35 (0.28) | 0.28 (0.26) | 0.27 (0.21) |

Table 3: Posterior probabilities and standard deviations as a function of viewing condition and test/retest session (N total number of participants).